

Existence and Uniqueness Theorem for Systems of First Order Linear IVP

Theorem 4.1

Consider the initial value problem

$$\mathbf{y}'(t) = P(t)\mathbf{y}(t) + \mathbf{g}(t), \quad \mathbf{y}(t_0) = \mathbf{y}_0,$$

where $\mathbf{y}(t)$, $P(t)$, $\mathbf{g}(t)$, and \mathbf{y}_0 are defined as in equation (2). Let the n^2 components of $P(t)$ and the n components of $\mathbf{g}(t)$ be continuous on the interval (a, b) , and let t_0 be in (a, b) . Then the initial value problem has a unique solution that exists on the entire interval (a, b) .

(Theorem 4.1 page 224 textbook)

Example:

Consider the initial value problem

$$y_1' = (\sin 2t)y_1 + \frac{t}{t^2 - 2t - 8}y_2 + 4, \quad y_1(1) = 2$$

$$y_2' = (\ln|t+1|)y_1 + e^{-2t}y_2 + \sec t, \quad y_2(1) = 0.$$

Determine the largest t -interval on which Theorem 4.1 guarantees the existence of a unique solution of this problem.

$$\vec{y}(t) = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \Rightarrow \vec{y}'(t) = \begin{pmatrix} y_1' \\ y_2' \end{pmatrix} = \underbrace{\begin{bmatrix} \sin(2t) & \frac{t}{(t-4)(t+2)} \\ \ln|t+1| & e^{-2t} \end{bmatrix}}_{P(t)} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} + \underbrace{\begin{bmatrix} 4 \\ \sec(t) \end{bmatrix}}_{\vec{G}(t)} \quad \begin{matrix} \vec{y}(1) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \\ \vec{y}(1) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} \end{matrix}$$

③ Look for possible discontinuities of $P(t)$ and components of $\vec{G}(t)$
 $t \neq 4, -2, -1, \pi/2, -\pi/2$

④ Place $t_0 = 1$ in \mathbb{R} ~~(1, 1)~~
 $-1 < t_0 = 1 < \pi/2$

⑤ Conclusion: theorem guarantees a unique solution over $(-1, \pi/2)$

Existence and Uniqueness Theorem for second order linear IVP

Let $p(t)$, $q(t)$, and $g(t)$ be continuous functions on the interval (a, b) , and let t_0 be in (a, b) . Then the initial value problem

$$y'' + p(t)y' + q(t)y = g(t), \quad y(t_0) = y_0, \quad y'(t_0) = y'_0$$

has a unique solution defined on the entire interval (a, b) .

(Theorem 3.1 page 111 textbook)

Ex: Determined the largest t-interval in which we can guarantee the existence and uniqueness of a solution of the IVP

• $ty'' + \cos(t)y + t^2y = t, \quad y(-1) = 1, \quad y'(-1) = 2$

$$\vec{y}(t) = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \in \mathbb{R}^2 \Rightarrow \vec{y}' = \begin{pmatrix} y_1' \\ y_2' \end{pmatrix} = \begin{pmatrix} y_2 \\ 1 + (-t - \frac{\cos(t)}{t})y_1 \end{pmatrix} = \begin{bmatrix} 0 \\ -t - \frac{\cos(t)}{t} \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

↳ get from scalar D.E.

① SF

$$\textcircled{2} y'' = 1 - ty - \frac{\cos(t)}{t}y = 1 - ty_1 - \frac{\cos(t)}{t}y_2$$

Theorem 4.1 $t \neq 0$ IVP 1)
look at $t_0 = -1$ IVP 2)
 $t_0 = 2$

$y_1 = y$ from def, y_2 from at vector \vec{y}
Theorem 4.1 guarantees the existence of a unique solution on $(-\infty, 0)$ and $(0, \infty)$
(IVP 1) (IVP 2)

• $ty'' + \cos(t)y + t^2y = t, \quad y(1) = 1, \quad y'(1) = 2$

$$\vec{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y \\ y' \end{pmatrix} \Rightarrow \vec{y}' = \begin{pmatrix} y_2 \\ 1 + (\frac{-\cos(t)}{t} - t)y_1 \end{pmatrix} = \vec{F}(t, \vec{y}) = \begin{pmatrix} f_1(t, \vec{y}) \\ f_2(t, \vec{y}) \end{pmatrix}$$

from the scalar D.E. $y'' = \frac{1 - \cos(t)}{t}y - ty = 1 + (\frac{-\cos(t)}{t} - t)y_1$

unique solution to IVP on $(0, \infty)$

① Can I write $\vec{F}(t, \vec{y}) = P(t)\vec{y} + \vec{G}(t)$?

$$\vec{y}' = \begin{bmatrix} 0 \\ -\frac{\cos(t)}{t} - t \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow \vec{y}' = P(t)\vec{y} + \vec{G}(t)$$

linear system

watch Gulite Lectures

Ex: Can you apply the same result to the IVP $ty'' + \cos(y)y + t^2y = t, \quad y(-1) = 1, \quad y'(-1) = 2$? Explain your answer.

$$\vec{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y \\ y' \end{pmatrix} \Rightarrow \vec{y}' = \begin{pmatrix} y_2 \\ y'' \end{pmatrix} = \begin{pmatrix} y_2 \\ 1 - ty_1 - \frac{\cos(y_1)}{t}y_1 \end{pmatrix}$$

$$\vec{y}' = \vec{F}(t, \vec{y})$$

↳ can't find a $P(t)$ and $\vec{G}(t)$ as the system is non-linear.

No